Open the black-box of self-supervised learning.

#### Yuandong Tian

**facebook** Artificial Intelligence

Research Scientist and Manager Facebook AI Research



#### Great Empirical Success







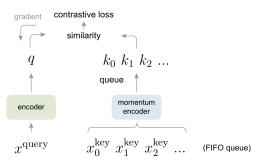


# Self-supervised Learning (SSL)

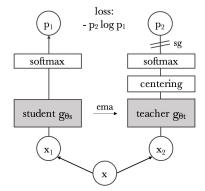
#### Reinforcement Learning (sparse reward signals)



Self-supervised Learning (dense signals)



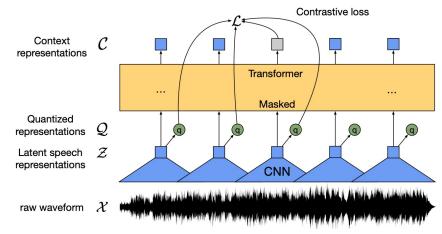
[K. He et al, Momentum Contrast for Unsupervised Visual Representation Learning, CVPR 2020]



[M. Caron et al, DINO: Emerging Properties in Self-Supervised Vision Transformers, ICCV 2021]



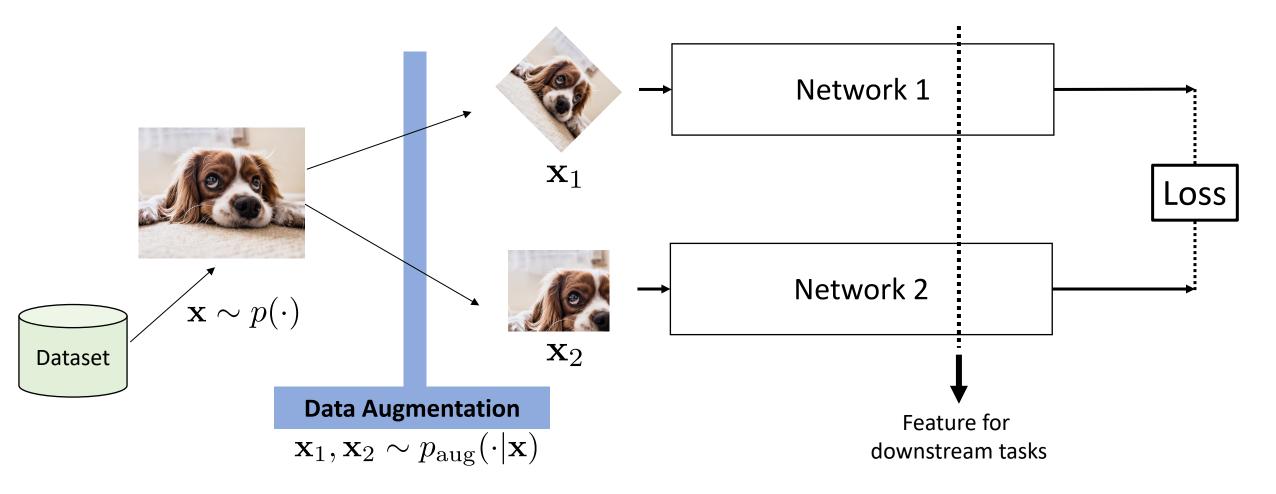
BERT, RoBERTa, ALBERT, etc



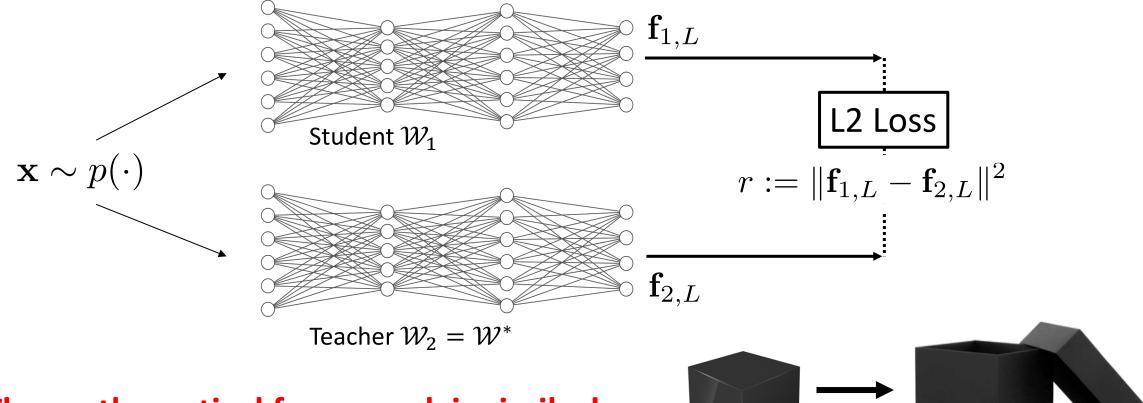
[A. Baevski et al, wav2vec 2.0: A Framework for Self-Supervised Learning of Speech Representations]

Learning Representation without Human Label!
 Why they work and achieve good performance? Can we do better?

## Self-supervised Learning (SSL)



#### Similarity with Teacher Student Setting

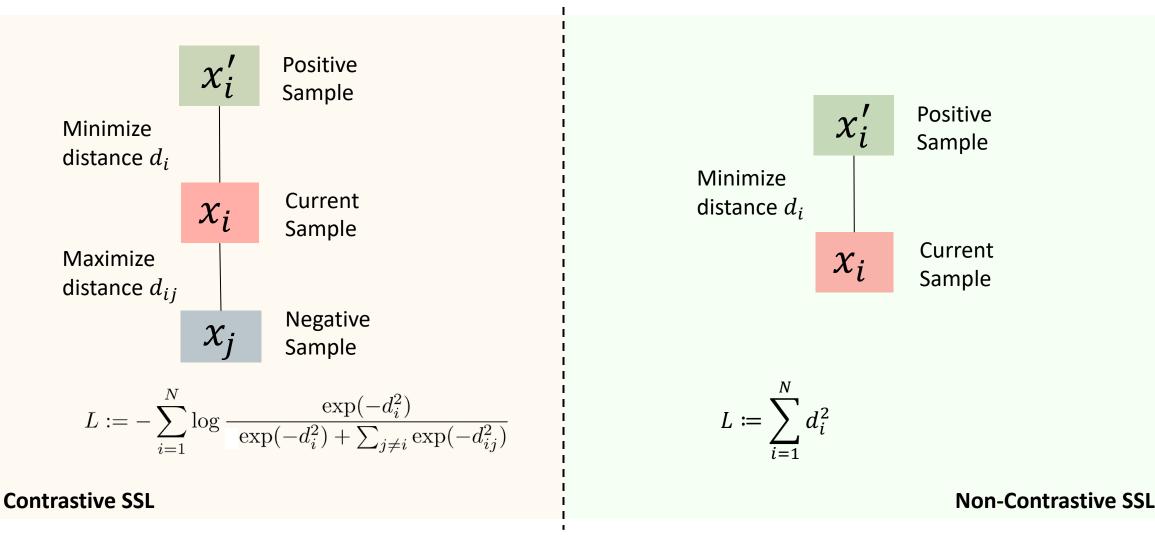


#### The mathematical framework is similar!

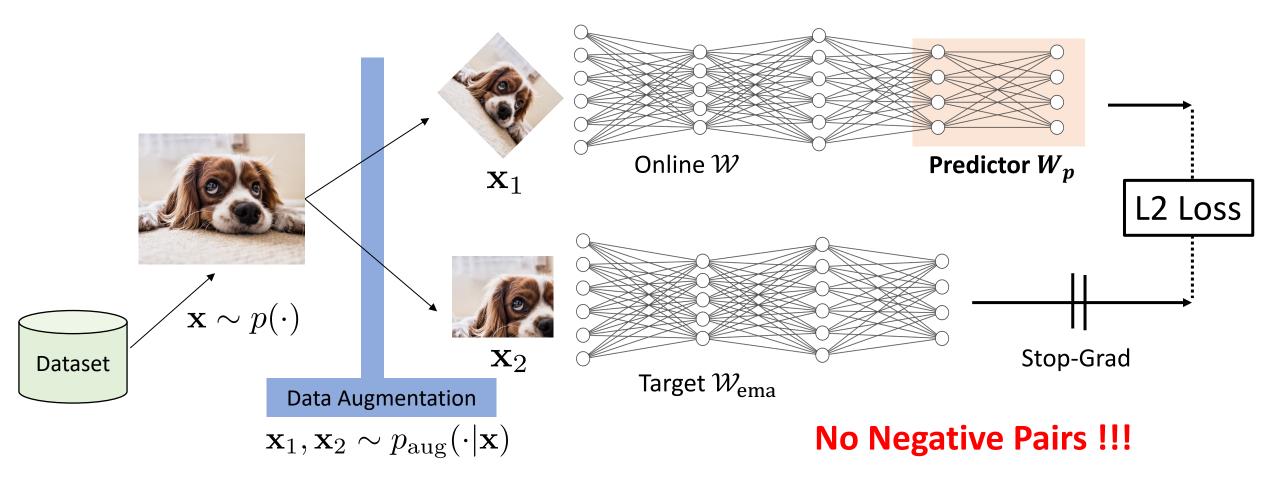
[Y. Tian, Student Specialization in Deep ReLU Networks With Finite Width and Input Dimension, ICML 2020]

facebook Artificial Intelligence [Z. Yang, Z. Chen, T. Cai, X. Chen, B. Li, Y. Tian, Understanding Robustness in Teacher-Student Setting: A New Perspective, AlStats 2021]

#### Contrastive versus Non-contrastive SSL

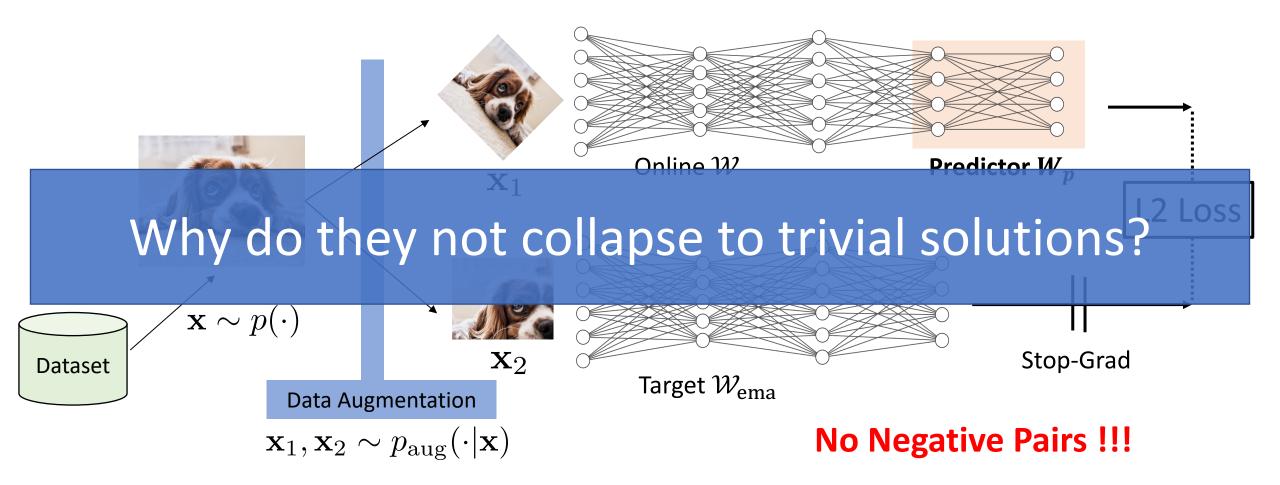


#### Non-contrastive SSL (BYOL/SimSiam)



**BYOL:** [J. Grill, Bootstrap your own latent: A new approach to self-supervised Learning, NeurIPS 2020] **SimSiam:** [X. Chen and K. He, Exploring Simple Siamese Representation Learning, CVPR 2021]

#### Non-contrastive SSL (BYOL/SimSiam)?



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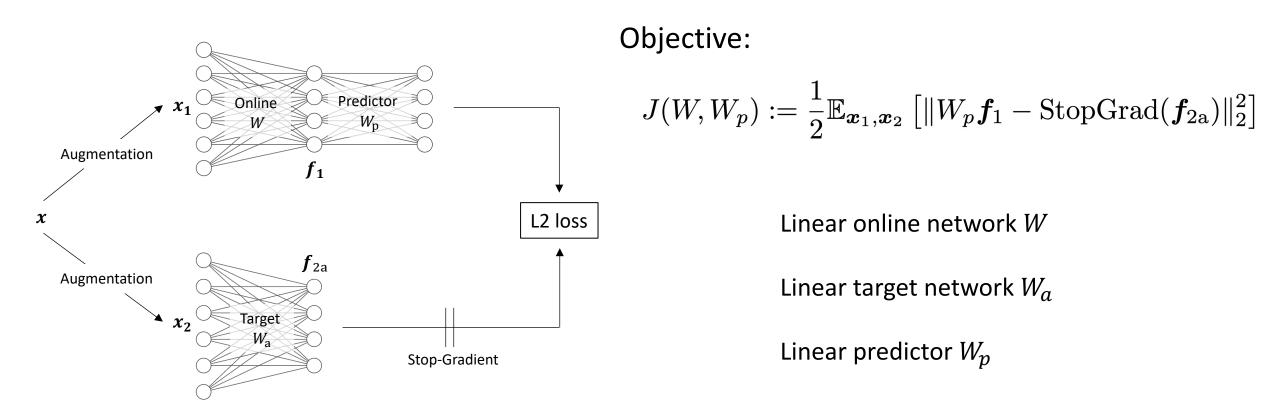
## A simple model





Yuandong Tian

Xinlei Chen Surya Ganguli



**DirectPred** [Y. Tian et al, Understanding Self-Supervised Learning Dynamics without Contrastive Pairs, *ICML'21 Outstanding Paper Honorable Mentions*]

# The Dynamics of Training Procedure

Lemma 1. BYOL learning dynamics following Eqn. 1:

$$\begin{split} \dot{W}_p &= \alpha_p \left( -W_p W(X + X') + W_a X \right) W^{\intercal} - \eta W_p \\ \dot{W} &= W_p^{\intercal} \left( -W_p W(X + X') + W_a X \right) - \eta W \\ \dot{W}_a &= \beta (-W_a + W) \end{split}$$

$$\begin{split} \bar{\boldsymbol{x}}(\boldsymbol{x}) &:= \mathbb{E}_{\boldsymbol{x}' \sim p_{\text{aug}}(\cdot | \boldsymbol{x})} \left[ \boldsymbol{x}' \right] \\ X &= \mathbb{E} \left[ \bar{\boldsymbol{x}} \bar{\boldsymbol{x}}^{\mathsf{T}} \right] \quad \text{Covariance of the data} \\ X' &= \mathbb{E}_{\boldsymbol{x}} \left[ \mathbb{V}_{\boldsymbol{x}' | \boldsymbol{x}} [\boldsymbol{x}'] \right] \quad \text{Covariance of the augmentation} \end{split}$$

Part I Why we need (1) an extra predictor and (2) stop-gradient?

Part II Why the system doesn't collapse to trivial solutions?

**Part III** The role played by different hyperparameters

Hyperparameter	Description
$lpha_p$	Relative learning rate of the predictor
η	Weight decay
β	The rate of Exponential Moving Average (EMA)

Part IV Novel non-contrastive SSL algorithm DirectPred

#### Part I No Predictor / No Stop-Gradient do not work

If there is no EMA ( $W = W_a$ ), then the dynamics becomes:

**No Predictor** 

$$\dot{W} = - (X' + \eta I) W$$
  
PSD matrix

No Stop-Gradient (Here 
$$\widetilde{W_p} \coloneqq W_p - I$$
)  

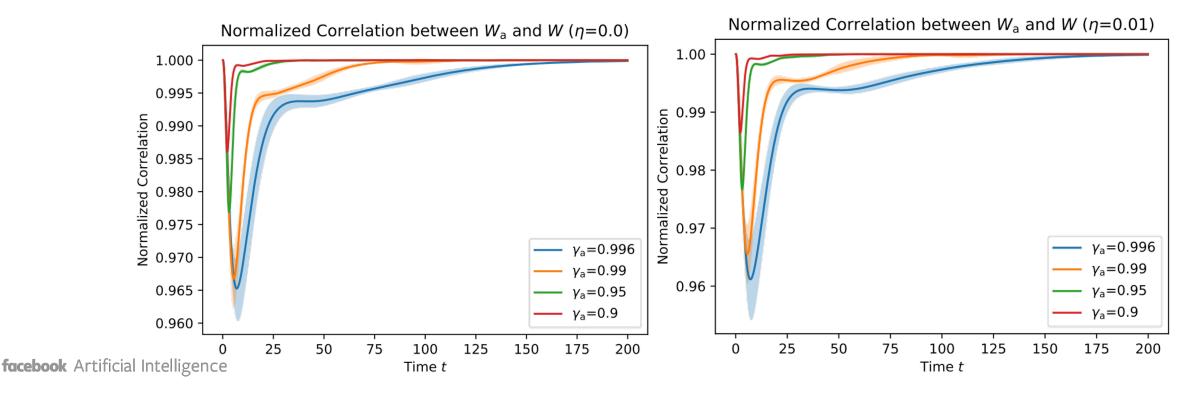
$$\frac{\mathrm{d}}{\mathrm{d}t} \operatorname{vec}(W) = -\left[X' \otimes (W_p^{\mathsf{T}} W_p + I) + X \otimes \widetilde{W}_p^{\mathsf{T}} \widetilde{W}_p + \eta I_{n_1 n_2}\right] \operatorname{vec}(W)$$
PSD matrix

In both cases,  $W \rightarrow 0$ 

#### Part II Assumptions

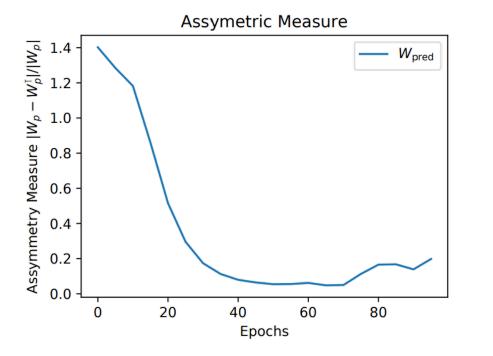
<u>Assumption 1</u> (Isotropic Data and Augmentation): X = I and  $X' = \sigma^2 I$ 

#### <u>Assumption 2</u>: the EMA weight $W_a(t) = \tau(t)W(t)$ is a linear function of W(t)

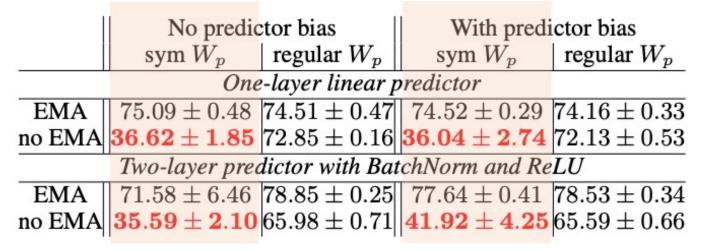


#### Symmetrization of the dynamics

<u>Assumption 3</u> (Symmetric predictor  $W_p$ ):  $W_p(t) = W_p^T(t)$ 



 $W_p$  becomes increasingly symmetric over training



Perfect symmetric  $W_p$  might hurt training

Under the three assumptions, the dynamics becomes:

$$\begin{split} \dot{W}_p &= -\frac{\alpha_p}{2}(1+\sigma^2)\{W_p,F\} + \alpha_p\tau F - \eta W_p \\ \dot{F} &= -(1+\sigma^2)\{W_p^2,F\} + \tau\{W_p,F\} - 2\eta F \\ &\{A,B\} \coloneqq AB + BA \text{ is the anti-commutator.} \end{split}$$

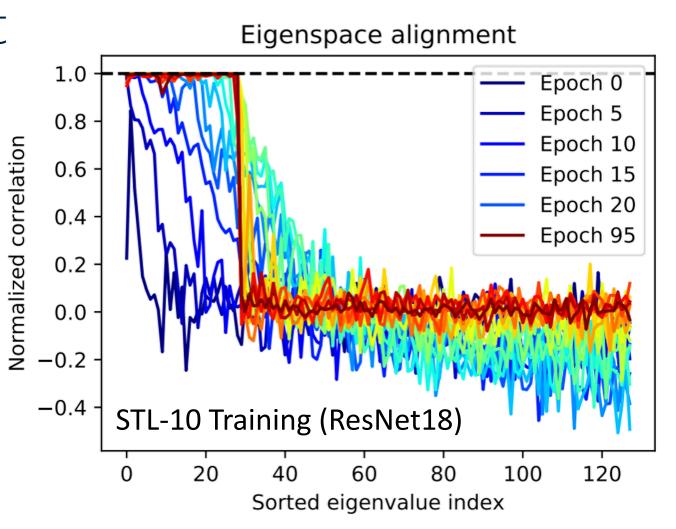
Here  $F \coloneqq E[ff^T] = WXW^T$  is the correlation matrix of the input of the predictor  $W_p$ . F is well-defined even with nonlinear network.

## Eigenspace Alignment

<u>Theorem 3</u>: Under certain conditions,

$$FW_p - W_p F \to 0$$

and the eigenspace of  $W_p$  and F gradually **aligns**.

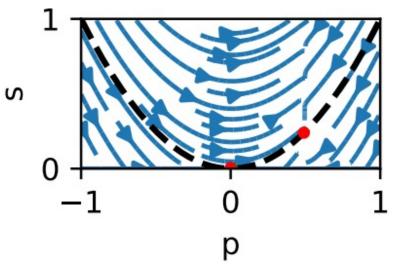


When eigenspace aligns, the dynamics becomes decoupled:

$$\dot{p}_j = \alpha_p s_j \left[ \tau - (1 + \sigma^2) p_j \right] - \eta p_j$$

$$\dot{s}_j = 2p_j s_j \left[ \tau - (1 + \sigma^2) p_j \right] - 2\eta s_j$$

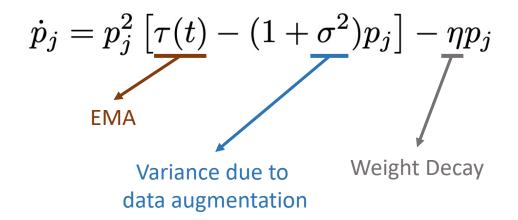
$$s_j \dot{\tau} = \beta (1 - \tau) s_j - \tau \dot{s}_j / 2.$$

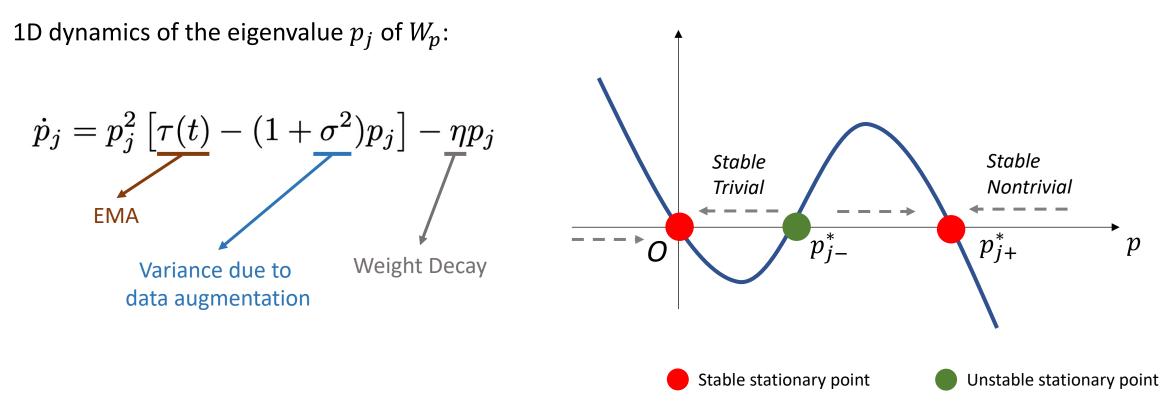


Where  $p_i$  and  $s_j$  are eigenvalues of  $W_p$  and F

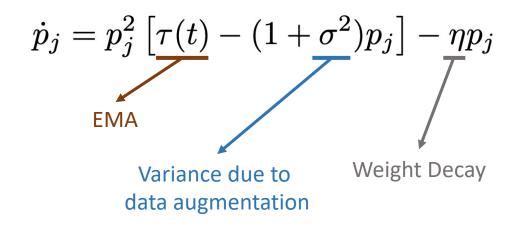
Invariance holds: 
$$s_j(t) = \alpha_p^{-1} p_j^2(t) + e^{-2\eta t} c_j$$

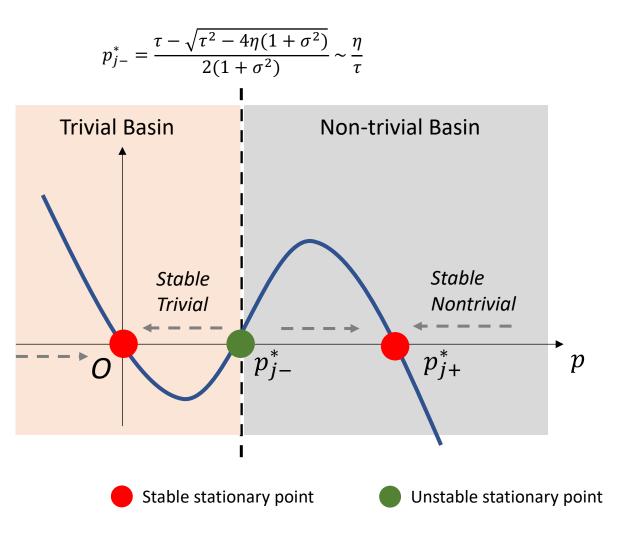
1D dynamics of the eigenvalue  $p_i$  of  $W_p$ :



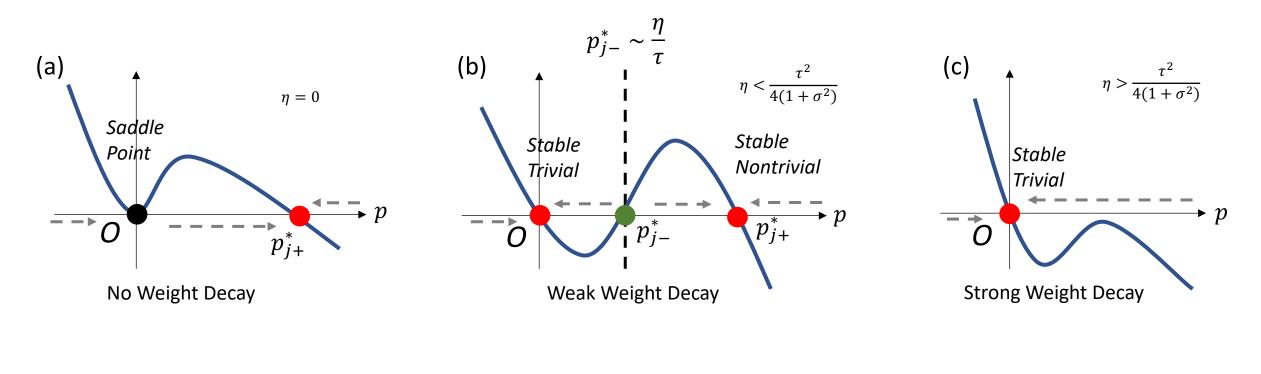


1D dynamics of the eigenvalue  $p_j$  of  $W_p$ :





## <u>Part III</u> The Effect of Weight Decay $\eta$



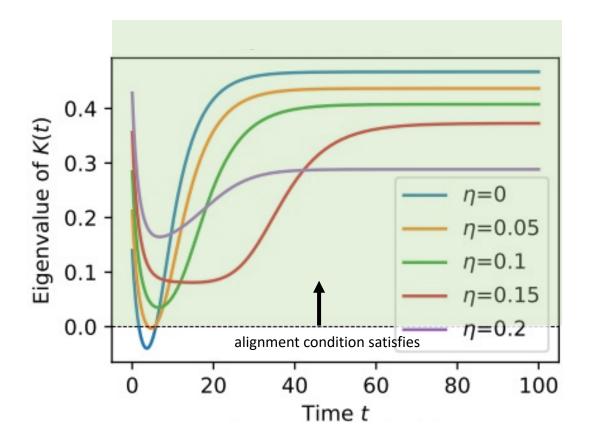
Stable stationary point

Unstable stationary point

## The Benefit of Weight Decay

Eigenspace alignment condition

$$p_j [\tau - (1 + \sigma^2) p_j] < \frac{1}{2} [\alpha_p (1 + \sigma^2) s_j + 3\eta]$$

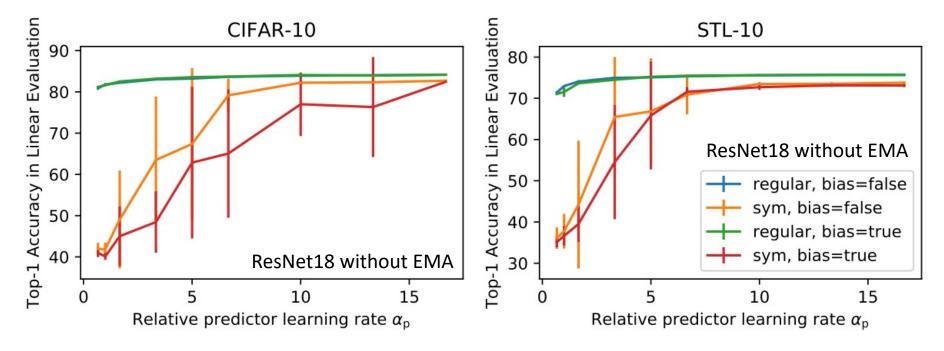


Higher weight decay  $\rightarrow$  alignment condition is more likely to satisfy!

# Relative learning rate of the predictor $lpha_p$

#### Positive ©

- 1. Large  $\alpha_p$  shrinks the size of trivial basin
- 2. Relax the condition of eigenspace alignment



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**Negative**  $\mathfrak{S}$  With very large  $\alpha_p$ , eigenvalue of F won't grow (and no feature learning)

Exponential Moving Average rate eta

 $\beta$  large  $\rightarrow W_a(t)$  catches W(t) faster  $\rightarrow \tau$  grows faster to 1

**Positive** O: Slower rate (small  $\beta$ ) relaxes the condition of eigenspace alignment

**Negative**  $\ensuremath{\mathfrak{S}}$ : Slower rate makes the training slow and expands the size of trivial basin

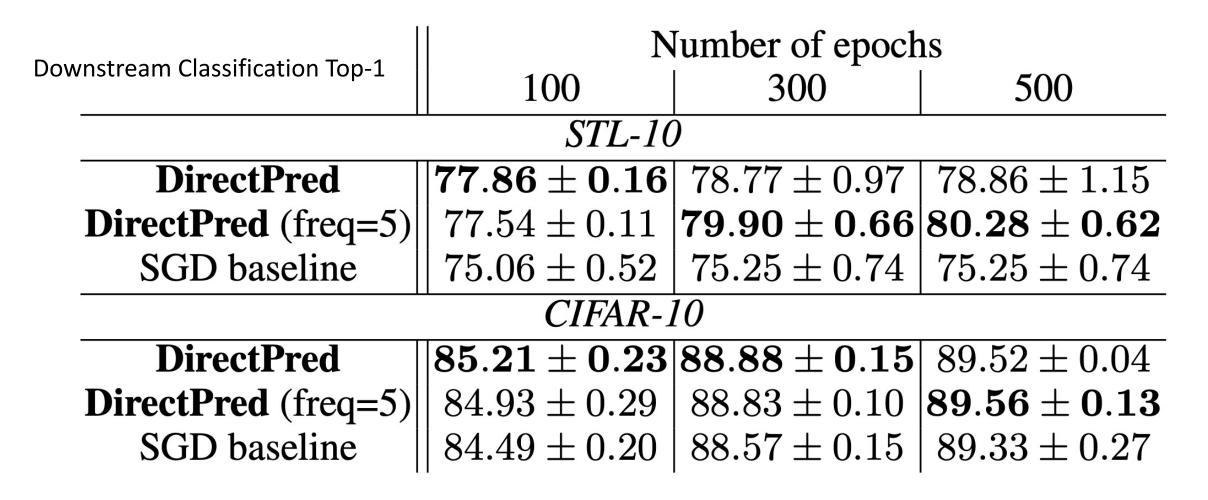
#### Part IV DirectPred

- Directly setting linear  $W_p$  rather than relying on gradient update.
  - 1. Estimate  $\hat{F} = \rho \hat{F} + (1 \rho) E[\boldsymbol{f} \boldsymbol{f}^T]$
  - 2. Eigen-decompose  $\widehat{F} = \widehat{U}\Lambda_F \widehat{U}^T$ ,  $\Lambda_F = \text{diag}[s_1, s_2, \dots, s_d]$
  - 3. Set  $W_p$  following the invariance:

$$p_j = \sqrt{s_j} + \epsilon \max_j s_j, \ W_p = \hat{U} \operatorname{diag}[p_j] \hat{U}^{\mathsf{T}}$$

#### **Guaranteed Eigenspace Alignment**

#### Performance of DirectPred on STL-10/CIFAR-10



## Performance of **DirectPred** on ImageNet

Downstream classification (ImageNet):

BYOL variants	Accuracy (60 ep)		Accuracy (300 ep)		
DIOL Variants	Top-1	Top-5	Top-1	Top-5	
2-layer predictor <sup>*</sup>	64.7	85.8	72.5	90.8	
linear predictor	59.4	82.3	69.9	89.6	
DirectPred	64.4	85.8	72.4	91.0	

\* 2-layer predictor is BYOL default setting.

DirectPred using linear predictor is better than SGD with linear predictor, and is comparable with 2-layer predictor.

## Summary

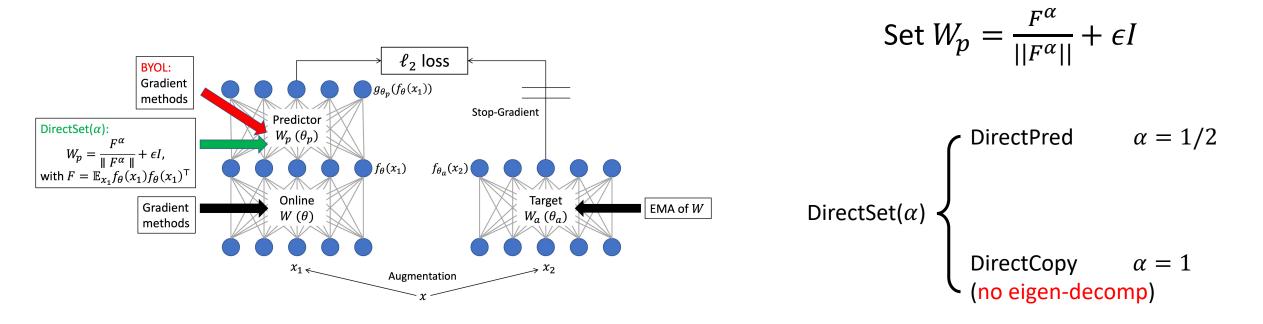
- A systematic analysis on the dynamics of non-contrastive selfsupervised learning (SSL) methods
  - **Part I** Why we need (1) an **extra predictor** and (2) **stop-gradient**?
  - **Part II** Why training doesn't **collapse** to trivial solutions?
  - **Part III** The role played by different hyperparameters
- Propose **DirectPred**, a novel non-contrastive SSL method
  - Directly align the eigenspace of the predictor  $W_p$  with the correlation matrix F
  - Comparable performance in downstream classification tasks, compared to vanilla BYOL
    - CIFAR-10/STL-10
    - ImageNet (60 epochs / 300 epochs)

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#### Code: <a href="https://github.com/facebookresearch/luckmatters/tree/master/ssl">https://github.com/facebookresearch/luckmatters/tree/master/ssl</a>

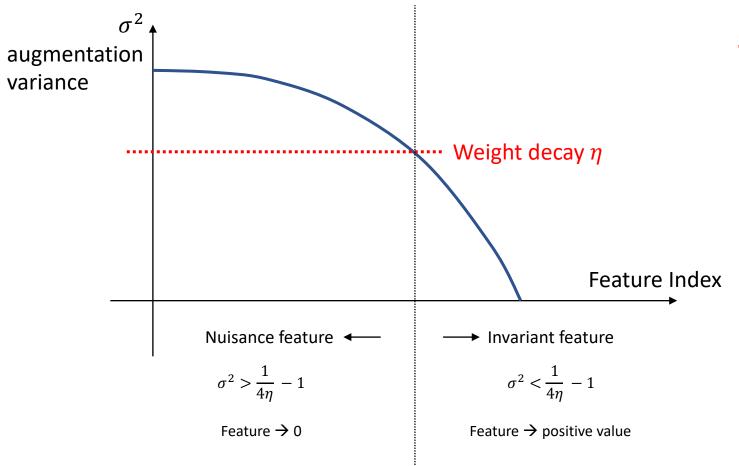
## Can we get rid of eigen-decomposition?

Propose **DirectSet**( $\alpha$ ):



**DirectCopy** [X. Wang, X. Chen, S. Du, Y. Tian, Towards Demystifying Representation Learning with Non-contrastive Self-supervision]

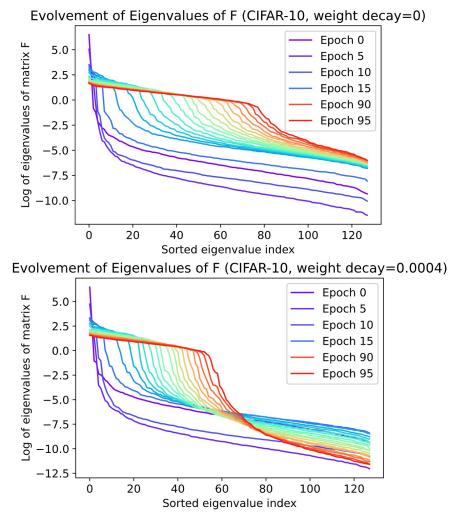
How DirectSet( $\alpha$ ) learns the feature?



<u>Assumption 1 (Isotropic Data and Augmentation):</u> X = I and  $X' = \sigma^2 I$ 

<u>Relaxed Assumption</u>  $X' = \sigma^2 P_B$  $P_B$ : Nuisance Subspace

## Effect of Weight Decay $\eta$



Performance Peaked at  $\eta = 4 \times 10^{-4}$ 

	Number of epochs			
	100 300			
STL-10				
$\eta = 0$	$71.94 \pm 0.93$	$78.53 {\pm} 0.40$		
$\eta = 0.0004$	$77.83{\pm}0.56$	$82.01{\pm}0.28$		
$\eta = 0.001$	$77.65 \pm 0.16$	$80.28 {\pm} 0.16$		
$\eta = 0.01$	$58.12 \pm 0.94$	$58.53 {\pm} 0.76$		
CIFAR-10				
$\eta = 0$	$79.15 \pm 0.08$	$85.35 {\pm} 0.31$		
$\eta = 0.0004$	$84.02{\pm}0.37$	$89.17{\pm}0.12$		
$\eta = 0.001$	$83.91 {\pm} 0.33$	$87.75 {\pm} 0.16$		
$\eta = 0.01$	$65.31{\pm}1.19$	$65.63 \pm 1.30$		

## The role played by $\alpha$ in DirectSet( $\alpha$ )

$$W \to \left(\frac{1+\sqrt{1-4\eta}}{2}\right)^{\frac{1}{2\alpha}} P_S$$

The larger the  $\alpha$ , the larger the signal-noise ratio

Why not use  $\alpha$  = 1? No eigen-decomposition!

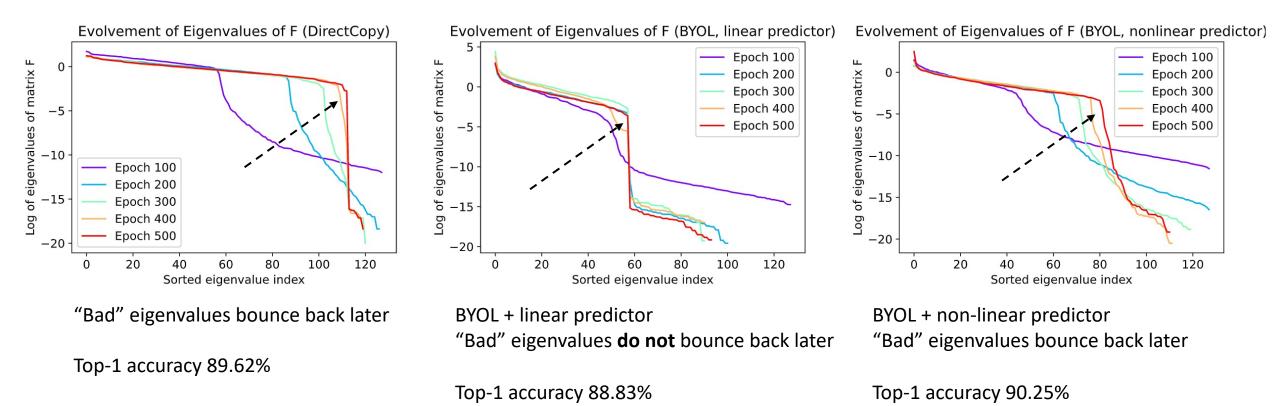
*P<sub>S</sub>*: Invariant Subspace

## Experimental Result of DirectSet( $\alpha$ )

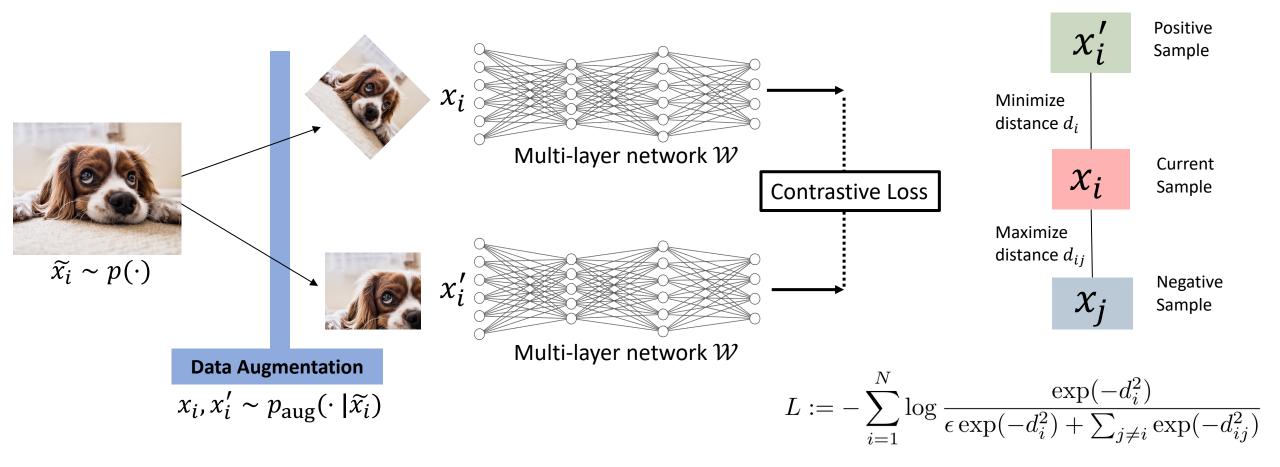
	Number of epochs				
	100	300			500
STL-10					
DirectCopy	$77.83 \pm 0.56$	$82.01\pm$	0.28	82.9	$5\pm0.29$
DirectPred	$77.86{\pm}0.16$	$78.77\pm$	0.97	78.8	$6 \pm 1.15$
DirectPred (freq=5)	$77.54 \pm 0.11$	$79.90 \pm$	0.66	80.2	$8 {\pm} 0.62$
SGD baseline	$75.06 \pm 0.52$	$75.25 \pm$	0.74	75.2	$5 \pm 0.74$
CIFAR-10					
DirectCopy	84.02±0.37	$89.17 \pm$	0.12	89.6	$2\pm0.10$
DirectPred	$85.21{\pm}0.23$	$88.88\pm$	0.15	89.5	$2{\pm}0.04$
DirectPred (freq=5)	84.93±0.29	$88.83\pm$	0.10	89.5	$6 {\pm} 0.13$
SGD baseline	$84.49 \pm 0.20$	$88.57 \pm$	0.15	89.3	$3{\pm}0.27$
	CIFAR-1	00			
DirectCopy	$55.40 \pm 0.19$	$61.06 \pm$	0.14	62.2	$3 \pm 0.06$
DirectPred	$56.60{\pm}0.27$	$61.65 \pm$	0.18	62.6	$8 {\pm} 0.35$
DirectPred (freq=5)	$56.43 \pm 0.21$	$oxed{62.01} \pm$	0.22	63.1	$5{\pm}0.27$
SGD baseline	$54.94{\pm}0.50$	$60.88\pm$	0.59	61.4	$2{\pm}0.89$
ImageNet (100 epoch)	Reported 2-layer	baseline	Direc	tPred	DirectCopy
Top-1 downstream accuracy	66.5		68	3.5	68.8

	Number of epochs			
	100 300			
STL-10				
$\alpha = 2$	$76.80 {\pm} 0.22$	$80.90 {\pm} 0.18$		
$\alpha = 1$	$77.83{\pm}0.56$	$82.01{\pm}0.28$		
$\alpha = 1/2$	$77.82 {\pm} 0.37$	$77.83 {\pm} 0.37$		
$\alpha = 1/4$	$76.82 {\pm} 0.36$	$76.82{\pm}0.36$		
CIFAR-10				
$\alpha = 2$	$82.96 \pm 0.56$	$88.60 {\pm} 0.11$		
$\alpha = 1$	$84.02 \pm 0.37$	$89.17{\pm}0.12$		
$\alpha = 1/2$	$84.88{\pm}0.21$	$88.32 {\pm} 0.57$		
$\alpha = 1/4$	$84.78 \pm 0.21$	$87.82 {\pm} 0.32$		

## Beyond Linear Models



#### Contrastive Self-supervised Learning

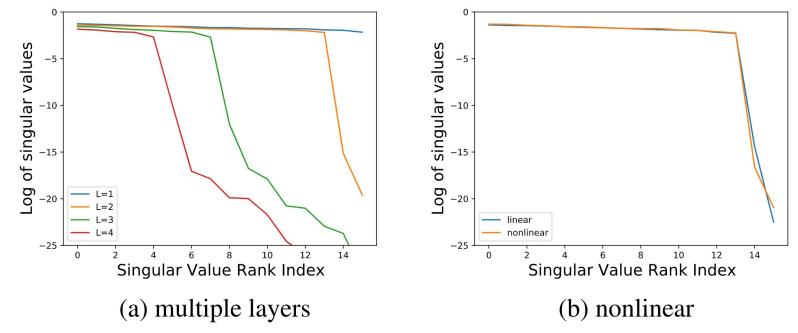


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**SimCLR** [T. Chen et al, A Simple Framework for Contrastive Learning of Visual Representations, ICML 2020]

## Contrastive SSL: Dimensional Collapsing

Shouldn't contrastive SSL make full use of all dimensions? The answer is No...



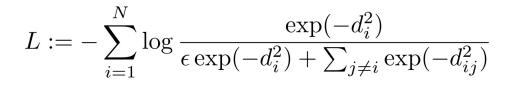
Two puzzling questions:

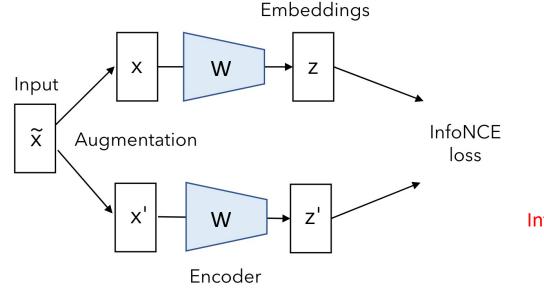
- 1. Why contrastive SSL still has collapsing issues?
- 2. Why L = 1 doesn't have collapsing, but  $L \ge 2$  has the issue?

facebook Artificial Intelligence DirectCLR [L. Jing, P. Vincent, Y. LeCun, Y. Tian, Understanding Dimensional Collapse in Contrastive Self-supervised Learning]

Property of InfoNCE

Linear Model





The dynamics can be written down as follows:

$$\frac{\mathrm{d}W}{\mathrm{d}t} = W(\Sigma_0 - \Sigma_{\mathrm{Aug}})$$

Inter-class covariance

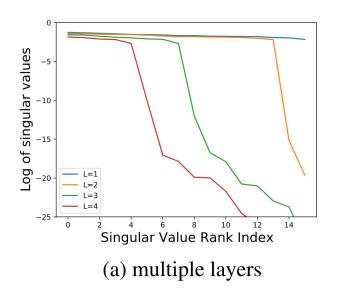
augmentation covariance

e 
$$\Sigma_0 \coloneqq \sum_{i,j} \alpha_{ij} (x_i - x_j) (x_i - x_j)^T$$
  
e  $\Sigma_{\text{aug}} \coloneqq \sum_i \left( \sum_{j \neq i} \alpha_{ij} \right) (x_i - x'_i) (x_i - x'_i)^T$ 

If  $\Sigma_0 - \Sigma_{aug}$  has negative eigenvalues, then W will be low-rank

## Deep Model leads to Dimensional Collapsing

- What if  $\Sigma_0 \Sigma_{Aug}$  is PSD?
- Still dimensional collapsing for deep models.

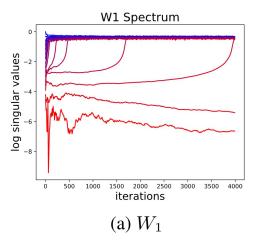


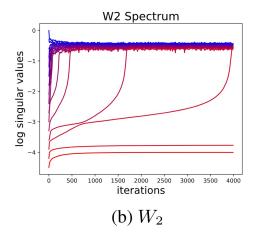
$$x \longrightarrow W_1 \longrightarrow W_2 \longrightarrow z$$

1.  $W_1$  and  $W_2$  will align with each other. 2. The dynamics of their singular values satisfy

$$\dot{\sigma}_{1}^{k} = \sigma_{1}^{k} (\sigma_{2}^{k})^{2} (\mathbf{v}_{1}^{k^{T}} X \mathbf{v}_{1}^{k}), \qquad \dot{\sigma}_{2}^{k} = \sigma_{2}^{k} (\sigma_{1}^{k})^{2} (\mathbf{v}_{1}^{k^{T}} X \mathbf{v}_{1}^{k})$$

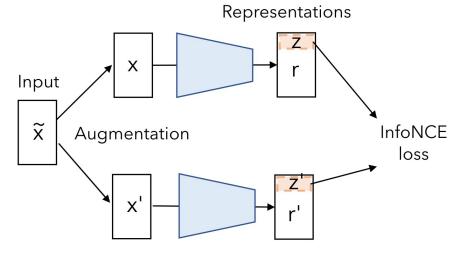
 $\sigma_1^k$  and  $\sigma_2^k$  grow much faster for k if  $(v_1^k)^T X v_1^k$  is large.





#### DirectCLR

• If things are aligned, why not let them align directly?



Loss function	Projector	Top-1 Accuracy
SimCLR	2-layer nonlinear projector	66.5
SimCLR	1-layer linear projector	61.1
SimCLR	no projector	51.5
DirectCLR	no projector	62.7

Encoder

